

#### **DISCRETE EVENT DYNAMIC SYSTEMS**

## **MARKOV CHAINS**

Pedro U. Lima

Instituto Superior Técnico (IST) Instituto de Sistemas e Robótica (ISR) Av.Rovisco Pais, 1 1049-001 Lisboa PORTUGAL

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#### MARKOV CHAINS Outline

- Definition of Markov Chain (MC) and relation to DES.
- Discrete Time MCs
  - the transition probability matrix
  - homogeneous MCs
  - state holding times
  - state probabilities
  - transient analysis
  - classification of states
  - steady-state analysis

- Continuous Time MCs
  - the transition rate matrix
  - homogeneous MCs
  - transition probabilities
  - state probabilities
  - transient analysis
  - steady-state analysis



### MARKOV CHAINS Definitions

**Def.:** A Markov Chain is a discrete state space stochastic process where the probability of transitions between states has the following property:  $P[X(t_{k+1}) = x_{k+1} | X(t_k) = x_k, X(t_{k-1}) = x_{k-1}, \dots] = P[X(t_{k+1}) = x_{k+1} | X(t_k) = x_k]$ 

#### Recall that, in a Markov process:

- All past state information is irrelevant (no state memory needed).
- How long the process has been in the current state is irrelevant (no state *age memory* needed).

#### **Discrete Time Markov Chains (DTMC)**

Stochastic sequence  $\{X_1, X_2, ...\}$  characterized by the Markov property :  $P[X_{k+1} = x_{k+1} | X_k = x_k, X_{k-1} = x_{k-1}, \cdots] = P[X_{k+1} = x_{k+1} | X_k = x_k]$ 



### **RELATION WITH DES**

**Relation with STA:** We will only be concerned with the total probability of making a transition from state *x* to state *x*', regardless of which event causes the transition:

$$p(x'|x) = P[X(t_{k+1}) = x'|X(t_k) = x] = \sum_{i \in \Gamma(x)} p(x'|x,i) \cdot p(i|x)$$

Therefore, to specify a (CT)MC model, we will only need to identify:

- 1. A state space  $\chi$
- 2. An initial state probability  $p_0(x)=P[X_0=x]$ , for all  $x \in \chi$
- 3. Transition probabilities p(x',x)

**Relation with ETPN**: The marking process of an exponential timed Petri net is a continuous time Markov Chain (CTMC).



#### **DISCRETE TIME MARKOV CHAINS (DTMC)**

**Transition probabilities** 
$$p_{ij}(k) = P[X_{k+1} = j | X_k = i]$$
  
 $0 \le p_{ij}(k) \le 1$   
 $\sum_{all j} p_{ij}(k) = 1$ 

# *n*-step transition probabilities $p_{ij}(k, k+n) \equiv P[X_{k+n} = j \mid X_k = i]$ $p_{ij}(k, k+n) = \sum_{\text{all } r} P[X_{k+n} = j \mid X_u = r, X_k = i] \cdot P[X_u = r \mid X_k = i], \ k < u \le k+n$

#### **Chapman-Kolmogorov Equations**

$$p_{ij}(k,k+n) = \sum_{\text{all } r} p_{ir}(k,u) p_{rj}(u,k+n), \ k < u \le k+n$$



#### **DISCRETE TIME MARKOV CHAINS (DTMC)**

**Chapman-Kolmogorov Equations (Matrix Form)** 

$$\mathbf{H}(k, k+n) \equiv [p_{ij}(k, k+n)], \quad i, j = 0, 1, 2, \dots$$

$$p_{ij}(k,k+n) = \sum_{\text{all } r} p_{ir}(k,u) p_{rj}(u,k+n), \ k < u \le k+n \quad \longrightarrow \quad \mathbf{H}(k,k+n) = \mathbf{H}(k,u)\mathbf{H}(u,k+n)$$

#### Forward Chapman-Kolmogorov Equation

$$u = k + n - 1 \quad \twoheadrightarrow \quad \mathbf{H}(k, k + n) = \mathbf{H}(k, k + n - 1)\mathbf{H}(k + n - 1, k + n)$$

#### **Backward Chapman-Kolmogorov Equation**

$$u = k + 1 \rightarrow \mathbf{H}(k, k + n) = \mathbf{H}(k, k + 1)\mathbf{H}(k + 1, k + n)$$

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Homogeneous MCs 
$$P[X(k+1) = j | X(k) = i] = \text{constant} = p_{ij}$$

The transition probabilities are independent of time *k*. Note that not all probabilities involved (e.g., joint probabilities) are time-independent.

$$p_{ij}^{n} \equiv P[X_{k+n} = j | X_{k} = i], n = 1, 2, ...$$

$$\mathbf{H}(k, k+n) = \mathbf{H}(n) = [p_{ij}^{n}], i, j = 0, 1, 2, ...$$

Setting u = k+m in the CK equation:

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**CK** equation

 $\mathbf{H}(n) = \mathbf{H}(n-1)\mathbf{H}(1)$ 



**Transition Probability Matrix** 

 $\mathbf{P} = [p_{ij}] = \mathbf{H}(1), i, j = 0, 1, 2, \dots$ 



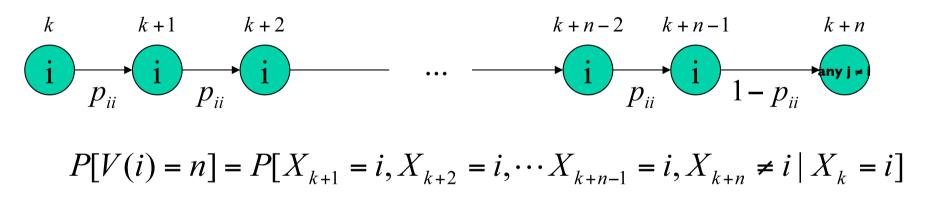


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#### **HOMOGENEOUS DTMC**

#### State Holding Times (Sojourn Times)

 $\mathcal{N}$  Random variable representing the number of consecutive time steps spent at state *i* 



 $P[V(i) = n] = (1 - p_{ii})p_{ii}^{n-1}$ 

Geometric distribution with parameter  $P_{ii}$ 



State Probabilities  

$$\begin{aligned} \pi_j(k) &\equiv P[X_k = j] \\ \pi(k) &= \left[\pi_0(k), \pi_1(k), \ldots\right] \\ 0 &\leq \pi_j(k) \leq 1 \\ \sum_{\text{all } j} \pi_j(k) &= 1 \end{aligned}$$

If, in addition to the state space  $\chi$  and the transition probability matrix **P** the initial state probability vector  $\pi(0) = [\pi_0(0), \pi_1(0), ...]$  is specified, the DTMC is completely specified.

Two types of analysis will be carried out:

- transient analysis
- steady-state analysis



**Transient Analysis** 

$$\pi_{j}(k+1) = P[X_{k+1} = j] = \sum_{\text{all } i} P[X_{k+1} = j \mid X_{k} = i] P[X_{k} = i] = \sum_{\text{all } i} p_{ij} \pi_{i}(k)$$

$$\pi(k+1) = \pi(k)\mathbf{P}, \ k = 0,1,...$$

Solution:

$$\pi(k) = \pi(0)\mathbf{P}^k, \ k = 1,2,...$$

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**Markov Chains** 

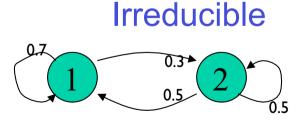


Reachable

Absorbing

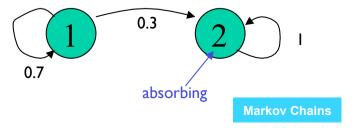
*j* is reachable from *i* if there is a path from *i* to *j*, i.e., if  $p_{ij}^{n} > 0$  for some n=1,2,...

A subset *S* of the state space  $\chi$  is said to be **closed** if  $p_{ij}=0$  for any  $i \in S$ ,  $j \notin S$ . State *i* is **absorbing** if it forms a single-element closed set  $(p_{ii}=1)$ . *i* is absorbing  $\Leftrightarrow \exists_{k_0}, \forall_{k \ge k_0} : \pi_i(k) = 1$ 



A closed set of states *S* is irreducible if state *j* is reachable from state *i* for any  $i,j \in S$ . A MC is **irreducible** if its state space  $\chi$  is irreducible.

Reducible, when there are subsets of the state space not reachable from other states (e.g., state 1 from 2 in the MC on the right)





Q.: The MC is in state *i*. Will the chain ever return to state *i*?A.:

- **definitely yes:** state *i* is **recurrent**
- maybe no: state *i* is transient

first time the chain enters *j*, starting in *i* 

Hitting time:
$$T_{ij} \equiv \min\{k > 0 : X_0 = i, X_k = j\}$$
Recurrence time: $T_{ii} \equiv \min\{k > 0 : X_0 = i, X_k = i\}, T_{ii} = 1, 2, ..., \infty$ 

.

$$\rho_i^k = P[T_{ii} = k]$$

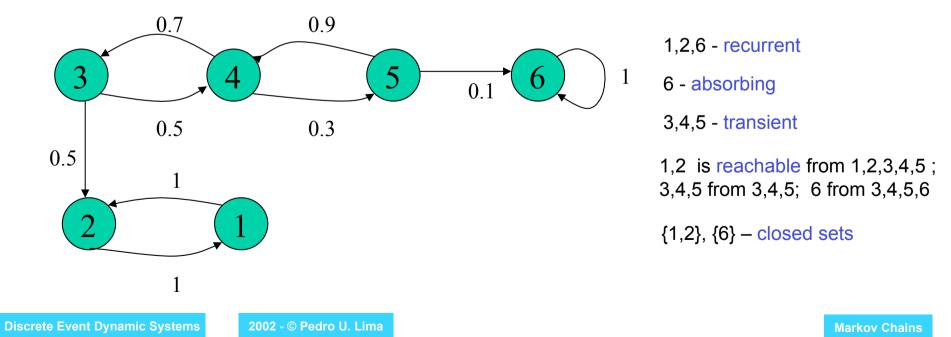
$$\rho_i = \sum_{k=1}^{\infty} \rho_i^k = P \text{ [ever return to } i \text{ | current state is } i\text{]} = P [T_{ii} < \infty]$$



**Recurrent** state *i* is recurrent if  $\rho_i = 1$ 

**Transient** state *i* is transient if  $\rho_i < 1$ 







**Theorem 1**: If a MC has a finite state space, then at least some state is *recurrent*.

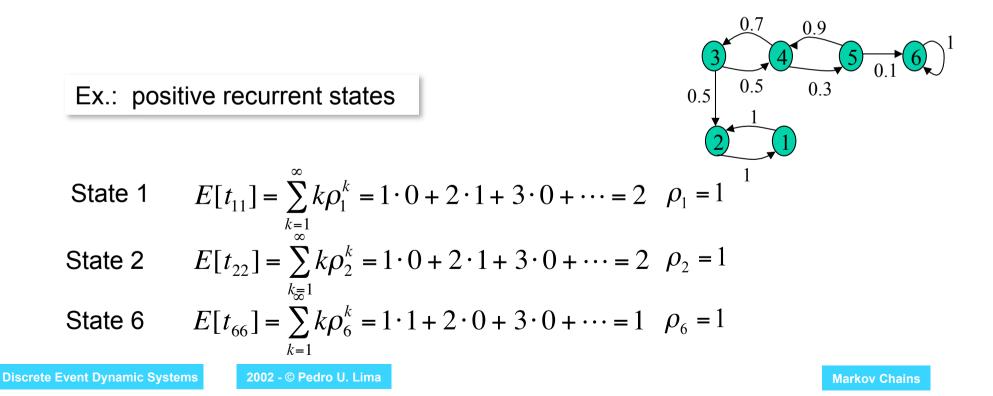
**Theorem 2**: If *i* is a *recurrent* state and *j* is reachable from *i*, then state *j* is *recurrent*.

**Theorem 3**: If S is a *finite closed irreducible* set of states, then every state in S is *recurrent*.



The mean recurrence time is  $M_i = E[t_{ii}] = \sum_{k=1}^{\infty} k \rho_i^k$ 

Null recurrentIf the mean recurrence time is $M_i = \infty$ Positive recurrentIf the mean recurrence time is $M_i < \infty$ 

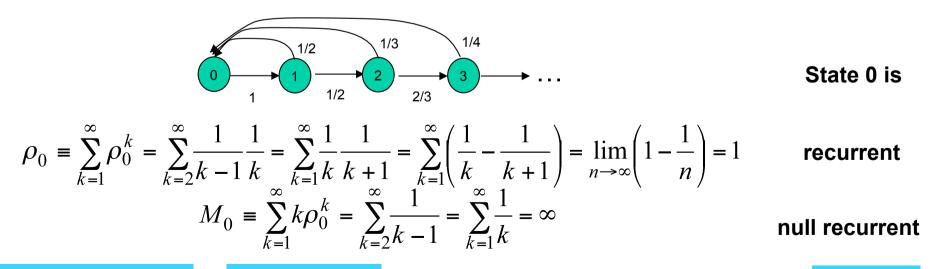




The mean recurrence time is  $M_i = E[t_{ii}] = \sum_{k=1}^{\infty} k \rho_i^k$ 

Null recurrentIf the mean recurrence time is $M_i = \infty$ Positive recurrentIf the mean recurrence time is $M_i < \infty$ 

Ex.: null recurrent states



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Transient states may never be revisited

Positive recurrent will definitely be revisited with finite expected recurrence time

Null recurrent will definitely be revisited but the expected recurrence time is infinite



**Theorem 4**: If *i* is a *positive recurrent* state and *j* is reachable from *i*, then state *j* is *positive recurrent*.

**Theorem 5**: If *S* is a *closed irreducible* set of states, then every state in *S* is *positive recurrent* or every state in *S* is *null recurrent* or every state in *S* is *transient*.

**Theorem 6**: If S is a *finite closed irreducible* set of states, then every state in S is *positive recurrent*.

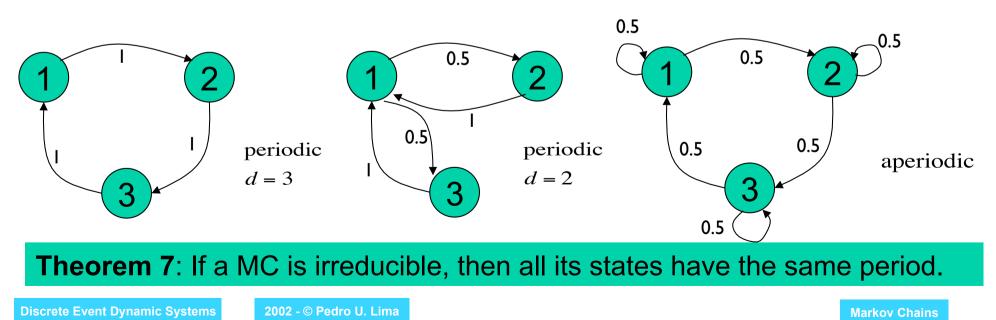


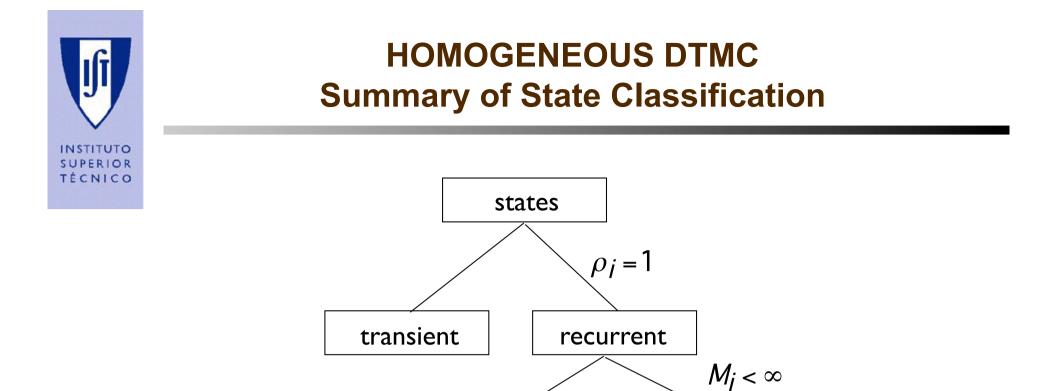
**Def.:** A state *i* is said to be *periodic* if the greatest common divisor *d* of the set  $\{n>0: p_{ii}^n>0\}$  is  $d \ge 2$ . If d=1, the state is said to be *aperiodic*.

Periodic State is visited every *d* steps

Aperiodic There's no *d* such that the state is visited regularly every *d* steps

Examples:





null recurrent

periodic



positive recurrent

 $d_i = 1$ 

aperiodic



#### **Steady-State Analysis**

**Q.:** What is the probability of finding a MC at state *i* in the long run, i.e., after a period of time long enough so that the state probabilities have reached fixed values which do not change with time?

 $\pi_j = \lim_{k \to \infty} \pi_j(k)$ 

Issues to be addressed:

- under what conditions do the above limits exist?
- if they exist, do they form a probability distribution, i.e.,  $\sum_{all i} \pi_j = 1$ ?
- how do we evaluate  $\pi_i$ ?

If  $\pi_j$  exists for some state *j*, it is referred as the *steady-state*, *equilibrium* or *stationary state probability*. If this is true for all states *j*, we obtain the *stationary probability vector*  $\pi = [\pi_0, \pi_1, ...]$ 



#### **Steady-State Analysis**

If the limits exist  $\pi_j(k+1) = \pi_j(k) \Rightarrow \pi = \pi P$ 

When the MC is *periodic*, the limits do not exist.

On the other hand,

**Theorem 8** – In an irreducible aperiodic MC the limits  $\pi_j = \lim_{k \to \infty} \pi_j(k)$ always exist and are independent of the initial state probability vector.



Steady-State Analysis – Irreducible MCs

**Recalling Theorem 5** 

If S is a *closed irreducible* set of states, then every state in S is *positive recurrent* or every state in S is *null recurrent* or every state in S is *transient*.

We get to the following two fundamental Theorems:

**Theorem 9**: In an irreducible aperiodic MC consisting of *null recurrent* or of *transient* states

$$\pi_j = \lim_{k \to \infty} \pi_j(k) = 0$$

For all states *j*, and no stationary probability distribution exists.

**Theorem 10**: In an irreducible aperiodic MC consisting of *positive recurrent* states, a unique stationary state probability vector  $\pi$  exists such that  $\pi_j > 0$  and

$$\pi_j = \lim_{k \to \infty} \pi_j(k) = \frac{1}{M_j}$$



In Theorem 9, *M<sub>i</sub>* is the *mean recurrence time* 

$$M_{j} \equiv E[t_{jj}] = \sum_{k=1}^{\infty} k \rho_{j}^{k}$$

and the steady state probabilities are determined by solving

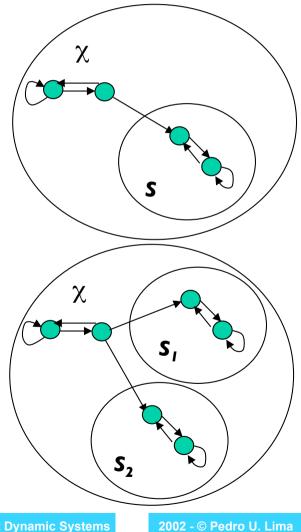
$$\pi = \pi \mathbf{P}$$
$$\sum_{\text{all } j} \pi_j = 1$$

Aperiodic positive recurrent states are very important and desirable – they are called **ergodic**. If all the states of a MC are ergodic, the MC is said to be **ergodic**.

From Theorems 6 and 10, every *finite* irreducible aperiodic MC has a unique stationary state probability vector determined by solving the above *finite* system equations. Note that solving an infinite system of equations is not so simple, though.



Steady-State Analysis – Reducible MCs



The chain eventually enters some irreducible closed set of states *S* and remains there forever:

• if *S* consists of 2 or more states, the steady state behavior of *S* can be analyzed as in the irreducible MC case

• if S consists of a single absorbing state, the MC simply remains in that state

The problem arises when the reducible chain contains two or more irreducible closed sets of states

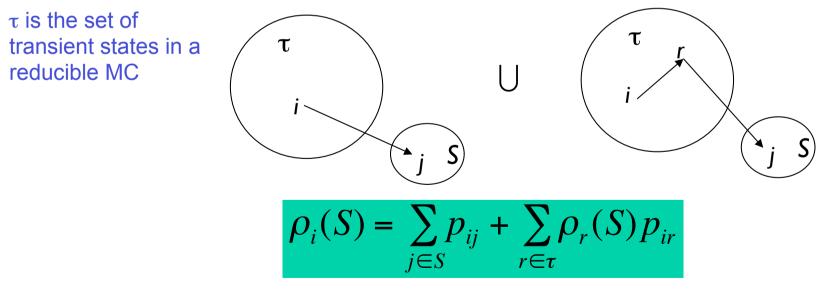
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Steady-State Analysis – Reducible MCs

In this case, the relevant question is: *what is the probability that the chain enters a particular set S first*?

**Def.:** probability that the chain enters set *S* given that it starts at state  $i \in \tau$ :  $\rho_i(S) \equiv P[X_k \in S \text{ for some } k > 0 | X_0 = i]$ 



The solution for the unknown probabilities  $\rho_i(s)$  for all  $i \in \tau$  is not easy, but it has a unique solution for a finite set  $\tau$ . However, if the set is infinite, the solution may not be unique.

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The Markov (memoryless) property is expressed here as  $P[X(t_{k+1}) = x_{k+1} | X(t_k) = x_k, X(t_{k-1}) = x_{k-1}, \cdots] = P[X(t_{k+1}) = x_{k+1} | X(t_k) = x_k],$   $t_0 \le t_1 \le \dots \le t_k \le t_{k+1}$ 

The analysis of CTMC parallels that of DTMC. However, the onestep probability matrix **P** can no longer be used since state transitions are no longer synchronized by a common clock.



**Transition functions** 

$$p_{ij}(s,t) = P[X(t) = j | X(s) = i], \ s \le t$$
$$p_{ij}(s,t) = \sum_{\text{all } r} P[X(t) = j | X(u) = r, X(s) = i] P[X(u) = r | X(s) = i]$$

#### **Chapman-Kolmogorov Equations**

$$p_{ij}(s,t) = \sum_{\text{all } r} p_{ir}(s,u) p_{rj}(u,t), \ s \le u \le t$$

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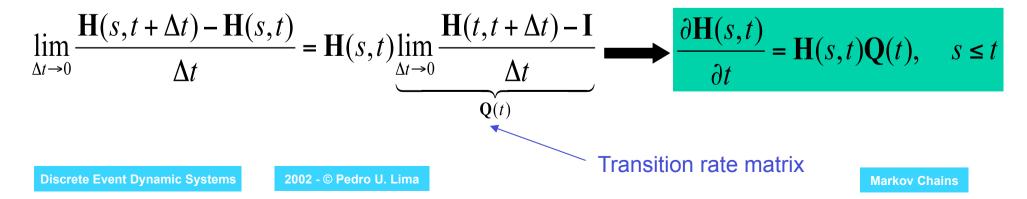
Chapman-Kolmogorov Equations (Matrix Form)

$$H(s,t) = [p_{ij}(s,t)], i, j = 0,1,2,...$$
$$H(s,s) = I$$

 $\mathbf{H}(s,t) = \mathbf{H}(s,u)\mathbf{H}(u,t), \quad s \le u \le t$ 

#### **The Transition Rate Matrix**

$$\mathbf{H}(s,t+\Delta t) = \mathbf{H}(s,t)\mathbf{H}(t,t+\Delta t), \quad s \le t \le t+\Delta t$$





**Backward Chapman-Kolmogorov Equation** 

$$\frac{\partial \mathbf{H}(s,t)}{\partial s} = -\mathbf{Q}(s)\mathbf{H}(s,t), \quad s \le s + \Delta s \le t$$

#### Forward Chapman-Kolmogorov Equation

$$\frac{\partial \mathbf{H}(s,t)}{\partial t} = \mathbf{H}(s,t)\mathbf{Q}(t), \quad s \le t \le t + \Delta t$$

**Solution of the FCK:** (under certain conditions that **Q** must satisfy)

$$\mathbf{H}(s,t) = \exp\left[\int_{s}^{t} \mathbf{Q}(\tau) d\tau\right]$$



$$p_{ij}(s, s + \tau) \equiv P[X(s + \tau) = j | X(s) = i] = p_{ij}(\tau)$$
  

$$\mathbf{H}(\tau) \rightarrow \mathbf{P}(\tau) \equiv [p_{ij}(\tau)], \quad i, j = 0, 1, 2, \dots$$
  

$$\sum_{\text{all } j} p_{ij}(\tau) = 1$$

Note that, for a homogeneous CTMC:  $\mathbf{H}(t,t+\Delta t) = \mathbf{P}(\Delta t)$ ,

therefore  $\mathbf{Q}(t) = \mathbf{Q} = \text{constant}$ 

$$\frac{d\mathbf{P}(\tau)}{d\tau} = \mathbf{P}(\tau)\mathbf{Q}$$
  
with i.c.  $p_{ij} = \begin{cases} 1 & \text{if } j = i \\ 0 & \text{if } j \neq i \end{cases}$  (\*)

Solution:

$$\mathbf{P}(t) = \exp[\mathbf{Q}t] = \mathbf{I} + \mathbf{Q}t + \mathbf{Q}^{2}t^{2} / 2! + \dots$$



#### State Holding Times (Sojourn Times)

V(i) Random variable representing the amount of time spent at state *i* whenever it is visited

$$P[V(i) \le t] = 1 - e^{-\Lambda(i)t}, \quad t \ge 0$$

Exponential distribution with parameter  $\Lambda(i)$ 

For MC, an *event* coincides with a *state transition*, therefore "interevent times" are identical to "state holding times".

Defining events  $e_{ij}$  as events generated by a Poisson process with rate  $\lambda_{ij}$  which cause transition from state *i* to state *j*:

$$\Lambda(i) = \sum_{e_{ij} \in \Gamma(i)} \lambda_{ij}$$



Physical Interpretation of the Properties of the Transition Rate Matrix

$$\frac{dp_{ij}(\tau)}{dt} = P(\tau)Q$$
with c.  $p_{ij} = \begin{cases} 1 & \text{if } j = i \\ 0 & \text{if } j \neq i \end{cases} \implies \frac{dp_{ij}(\tau)}{d\tau} = p_{ij}(\tau)q_{jj} + \sum_{r \neq j} p_{ir}(\tau)q_{rj}$ 

$$q_{ii} = \frac{d}{d\tau} [p_{ii}(\tau)]_{\tau=0} \text{ Note that: } -q_{ii} = \frac{d}{d\tau} [1 - p_{ii}(\tau)]_{\tau=0} = \Lambda(i)$$

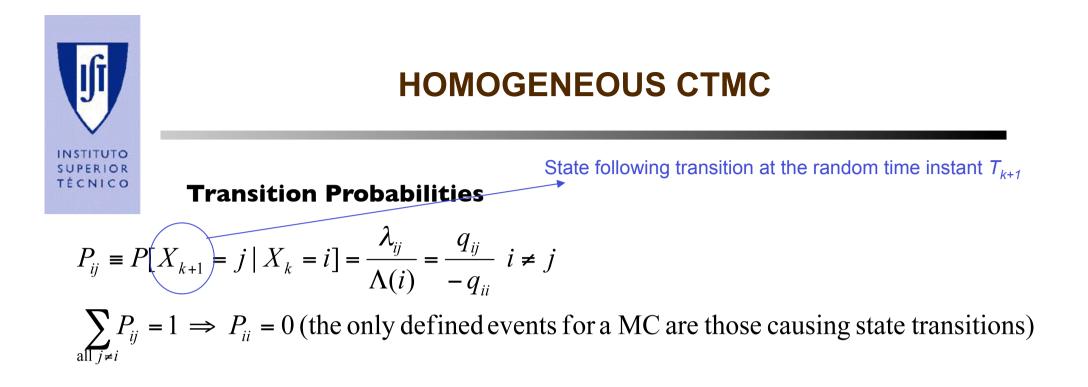
 $-q_{ii}$  is the *instantaneous rate* at which a state transition out of *i* takes place.

$$q_{ij} = \frac{dp_{ij}(\tau)}{d\tau}\bigg|_{\tau=0} = \lambda_{ij}$$

 $q_{ii}$  is the *instantaneous rate* at which a state transition from *i* to *j* takes place.

$$\sum_{\substack{i \in \mathcal{I} \\ \text{all } j \\ \text{Differentiating w.r.t. } \tau \text{ and setting } \tau=0} \sum_{\substack{i \in \mathcal{I} \\ \text{all } j \\ \text{all$$

0



Once **Q** is specified, a full MC model specification is obtained:

- $P_{ij}$  determined as above
- the parameters of the exponential state holding time are given by

$$-Q_{ii} = \sum_{j \neq i} Q_{ij}$$



State Probabilities  

$$\begin{aligned} \pi_{j}(t) &= P[X(t) = j] \\ \pi(t) &= \left[\pi_{0}(t), \pi_{1}(t), \ldots\right] \\ 0 &\leq \pi_{j}(t) \leq 1 \\ \sum_{\text{all } j} \pi_{j}(t) &= 1 \end{aligned}$$

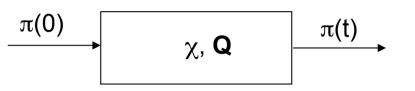
If, in addition to the state space  $\chi$  and the transition matrix  $\mathbf{P}(\tau)$ , the initial state probability vector  $\pi(0) = [\pi_0(0), \pi_1(0), ..]$  is specified, the CTMC is completely specified.

Notice that  $P(\tau) = e^{Q\tau}$ , therefore the specification of **Q** is enough.

Two types of analysis will be carried out:

- transient analysis
- steady-state analysis





**Transient Analysis**  $\pi_{j}(t) = P[X(t) = j] = \sum_{\text{all } i} P[X(t) = j \mid X(0) = i] P[X(0) = i] = \sum_{\text{all } i} p_{ij}(t) \pi_{i}(0)$ 

$$\pi(t) = \pi(0)\mathbf{P} = \pi(0)e^{\mathbf{Q}t}$$

This is the solution of:

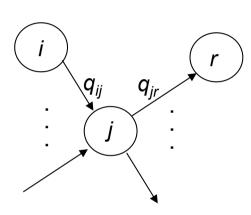
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$$\frac{d\pi(t)}{dt} = \pi(t)\mathbf{Q} (**)$$

Markov Chains



State transition rate diagram



Total flow into state  $j = \sum_{i \neq j} q_{ij} \pi_i(t)$ Total flow out of state  $j = \sum_{r \neq j} q_{jr} \pi_j(t)$ 

Net probability flow rate into state *j* :

$$\frac{d\pi_{j}(t)}{dt} = \sum_{i \neq j} q_{ij} \pi_{i}(t) - \left(\sum_{r \neq j} q_{jr}\right) \pi_{j}(t)$$
  
but  $\sum q_{jr} = -q_{jj}$ 

 $\int dt \sum_{r \neq j} q_{jr} - q_{jr}$ 

therefore

$$\frac{d\pi_j(t)}{dt} = q_{jj}\pi_j(t) + \sum_{i \neq j} q_{ij}\pi_i(t)$$

exactly the same as (\*\*)

Therefore the state transition rate diagram contains the exact same information as the transition rate matrix Q

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#### **Steady-State Analysis**

**Q.:** What is the probability of finding a MC at state *i* in the long run, i.e., after a period of time long enough so that the state probabilities have reached fixed values which do not change with time?

 $\pi_j = \lim_{t \to \infty} \pi_j(t)$ 

Issues to be addressed:

- under what conditions do the above limits exist?
- if they exist, do they form a probability distribution, i.e.,  $\sum_{a \parallel i} \pi_j = 1$ ?
- how do we evaluate  $\pi_i$ ?

If  $\pi_j$  exists for some state *j*, it is referred as the *steady-state*, *equilibrium* or *stationary state probability*. If this is true for all states *j*, we obtain the *stationary probability vector*  $\pi = [\pi_0, \pi_1, ..]$ 

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**Steady-State Analysis** 

If the limits exist 
$$\frac{d\pi(t)}{dt} = 0 \implies \pi \mathbf{Q} = \mathbf{0}$$

All the results for CTMC parallel those for DTMC. We will state only the most relevant result.

**Theorem 11**: In an irreducible CTMC consisting of *positive recurrent* states, a unique stationary state probability vector  $\pi$  exists such that  $\pi_j > 0$  and  $\pi_j = \lim_{t \to \infty} \pi_j(t)$ 

and the steady state probabilities are determined by solving  $\sum_{j=1}^{n} \pi_j = 1$ 

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$$\pi Q = C$$



#### **RELATION WITH ETPNs**

State space of the equivalent CTMC: reachability set  $R[x_0]$  of the exponential timed Petri net

Computation of the transition rate from state  $x_i$  to state  $x_j \neq x_i$  is given by

$$q_{ij} = \sum_{t_k \in T_{ij}} \lambda_k(x_i)$$

Where  $T_{ij}$  is the subset of  $T_D$  enabled transitions in  $x_i$  such that the firing of any transition in  $T_{ij}$  leaves the CTMC in  $x_j$ .

If 
$$x_j = x_i$$
,  $q_{ii} = -\sum_{j \neq i} q_{ij}$ 



### **MARKOV CHAINS**

#### **Further reading**

• Birth-Death chains – special structure facilitates the task of obtaining explicit solutions for state probabilities (steady-state and transient analysis).

Lots of literature on Markov Chains

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